

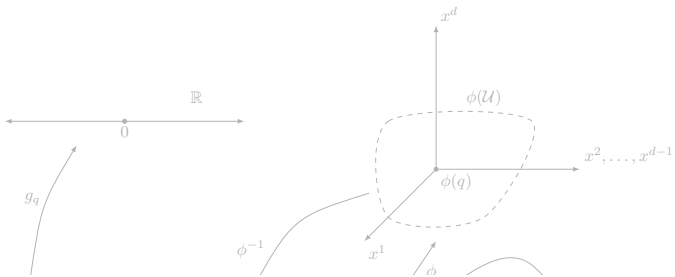
# Excerpts from *Geometric Bayes*

Andrew J. Holbrook

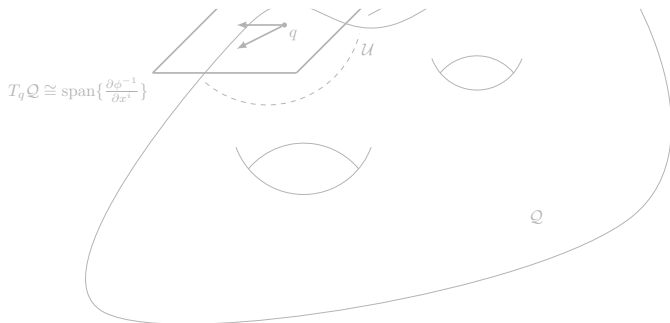
Department of Statistics  
University of California, Irvine

Department of Human Genetics  
University of California, Los Angeles

JSM 2019



## Part 1. The Story of Super Chris





This is Super Chris.

Super Chris is handsome.





Super Chris is very smart.

## Sequence of events

Item:

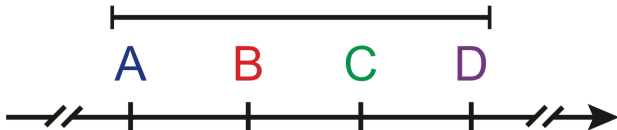
A

B

C

D

Time:



Sequence position:

1

2

3

4

## Sequence of odors in rats

vacuum



odor



Odor

A

Odor

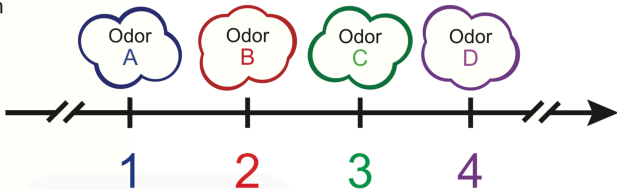
B

Odor

C

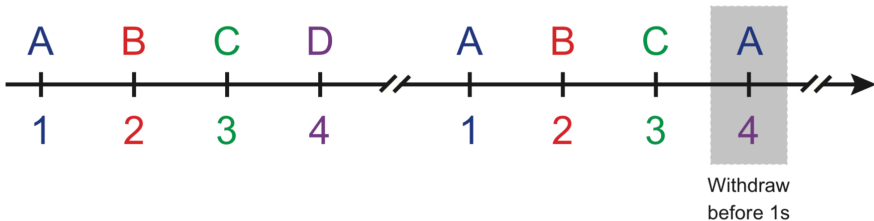
Odor

D



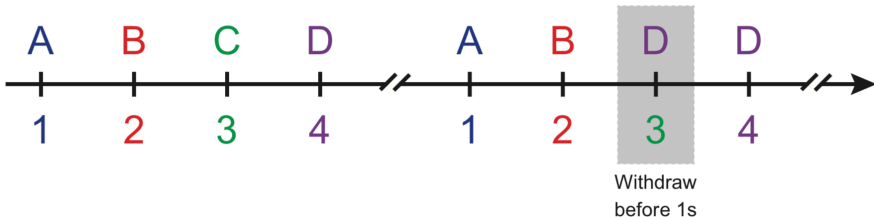
All items "in sequence"

One item "out of sequence" (*Repeat*)

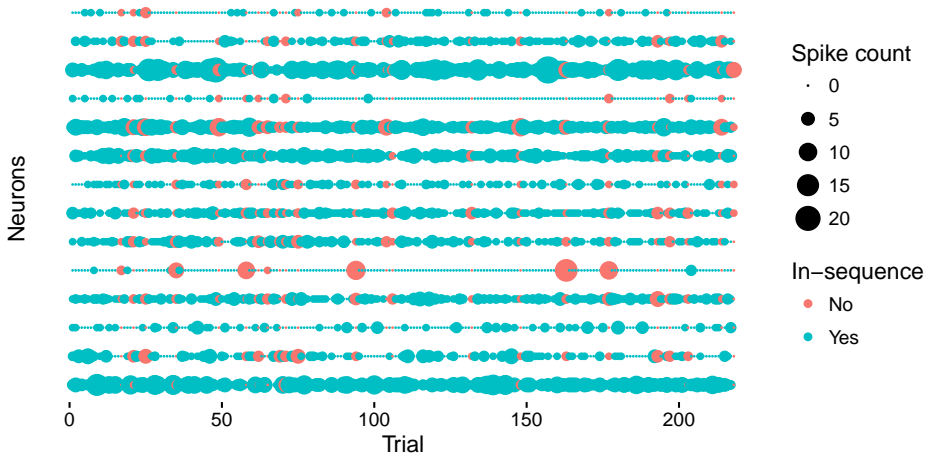


All items "in sequence"

One item "out of sequence" (*Skip*)

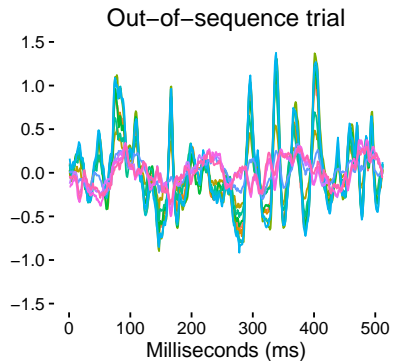
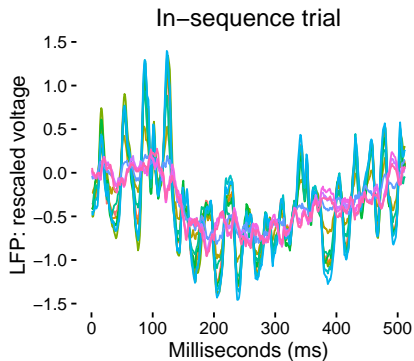


# Neural spike trains





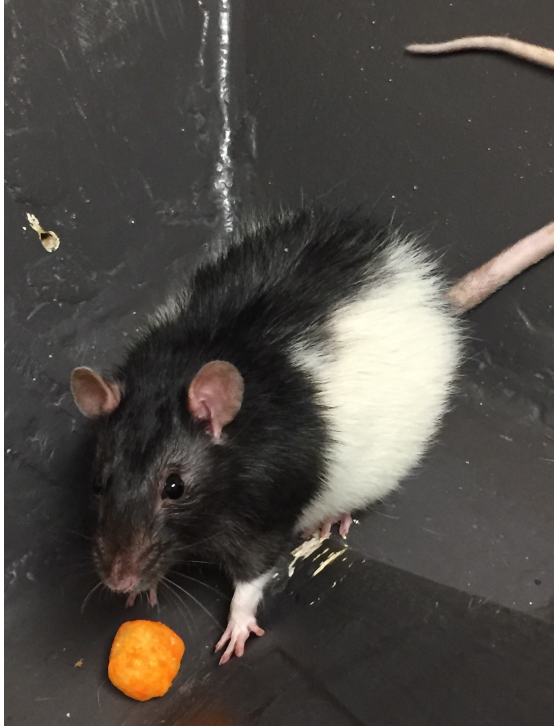
# Local field potentials

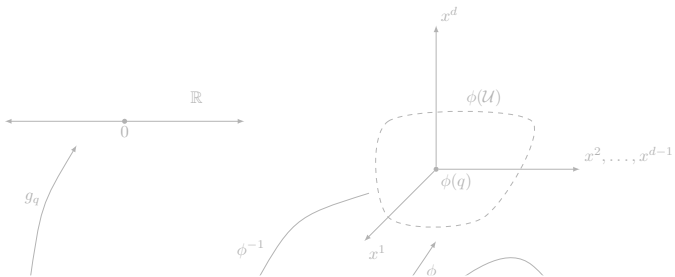




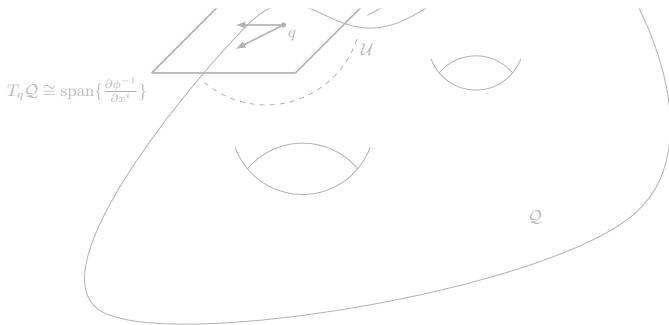
Super Chris gets it right!

Well done, Super Chris!

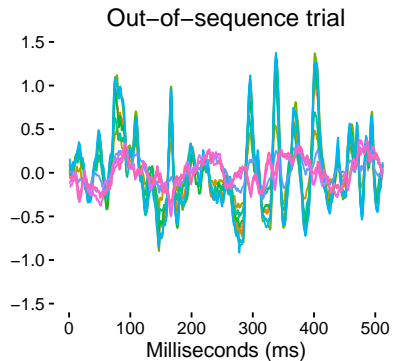
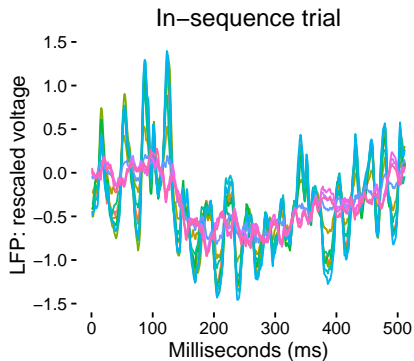




## Part 2. Dependencies between brain signals



# Local field potentials



# Spectral density and coherence

Auto-covariance matrix at lag  $\ell$ :

$$\Gamma_\ell = \text{Cov}(y(t), y(t - \ell)) = \mathbb{E}\left((y(t) - \mu)(y(t - \ell) - \mu)^T\right)$$

Power spectral density matrix at frequency  $\omega$ :

$$\Sigma(\omega) = \sum_{\ell=-\infty}^{\infty} \Gamma_\ell \exp(-i2\pi\omega\ell)$$

The squared coherence matrix at frequency  $\omega$ :

$$\rho_{ij}^2(\omega) = \frac{|\Sigma_{ij}(\omega)|^2}{\Sigma_{ii}(\omega) \Sigma_{jj}(\omega)}$$

# The Whittle likelihood

For  $\omega_k = \frac{k}{T}$  and  $k = -(\frac{T}{2} - 1), \dots, \frac{T}{2}$ , define

$$Y(\omega_k) = \frac{1}{\sqrt{T}} \sum_{t=1}^T y(t) \exp(-i2\pi\omega_k t).$$

In many situations, we have

$$Y(\omega_k) \stackrel{ind}{\sim} \text{CN}_d(0, \Sigma(\omega_k)),$$

and it is common to assume

$$Y(\omega_k) \stackrel{iid}{\sim} \text{CN}_d(0, \Sigma_\alpha)$$

for  $\alpha$  a band of frequencies.

# Convenient and inconvenient priors

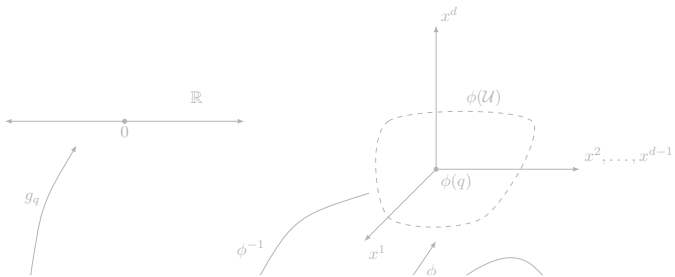
Table 1: Priors for positive definite matrices

Prior	Symmetric	Hermitian
Wishart	$ \Sigma ^{(n-d-1)/2} \exp(-\text{tr}\{\Psi^{-1}\Sigma\}/2)$	$ \Sigma ^{n-d} \exp(-\text{tr}\{\Psi^{-1}\Sigma\})$
inverse-Wishart	$ \Sigma ^{-(n+d+1)/2} \exp(-\text{tr}\{\Psi\Sigma^{-1}\}/2)$	$ \Sigma ^{-(n+d)} \exp(-\text{tr}\{\Psi\Sigma^{-1}\})$
uniform	1	1
Jeffreys	$ \Sigma ^{-(d+1)/2}$	$ \Sigma ^{-d}$
reference	$( \Sigma  \prod_{i < j} (d_i - d_j))^{-1}$	$( \Sigma  \prod_{i < j} (d_i - d_j)^2)^{-1}$

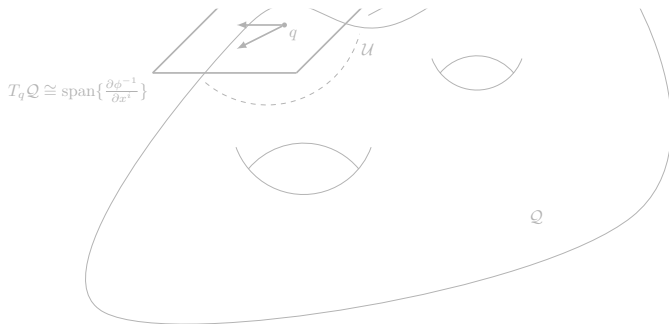
Inference technique should:

- ▶ give freedom to choose
- ▶ not require complicated parameterizations
- ▶ be exact

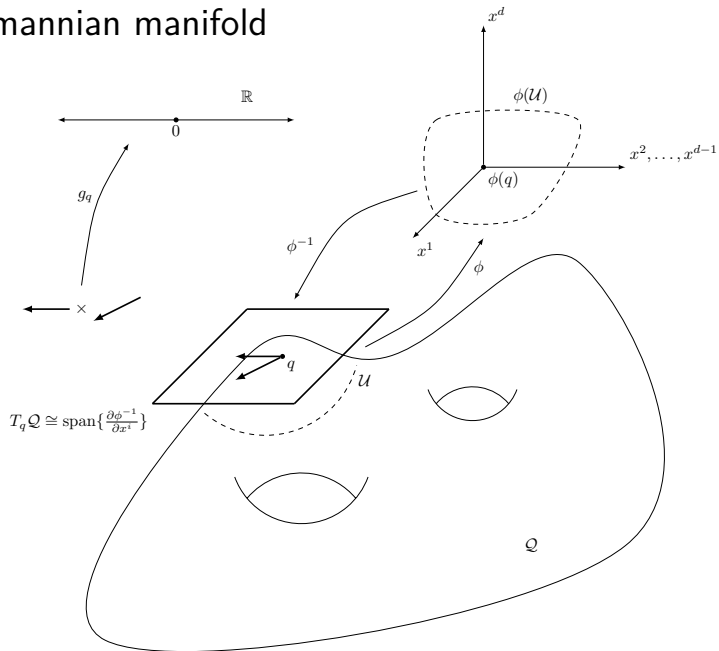




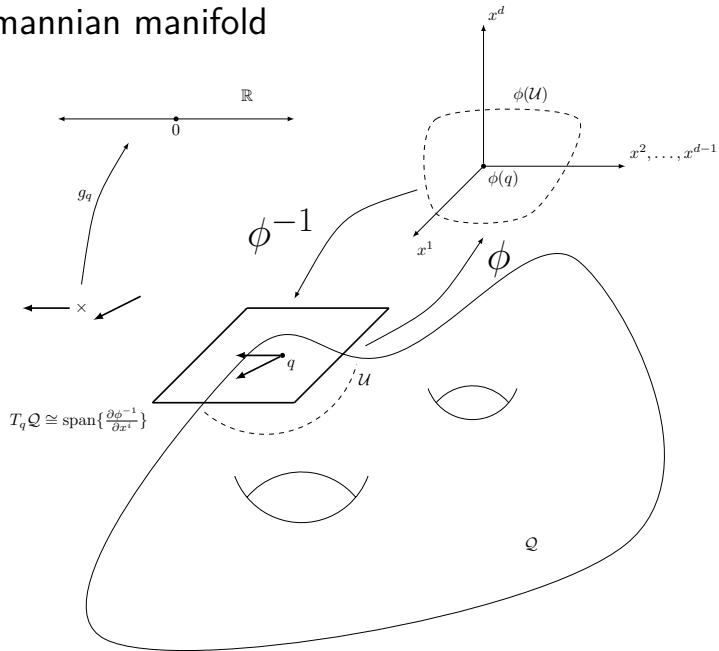
### Part 3. A Geometric digression



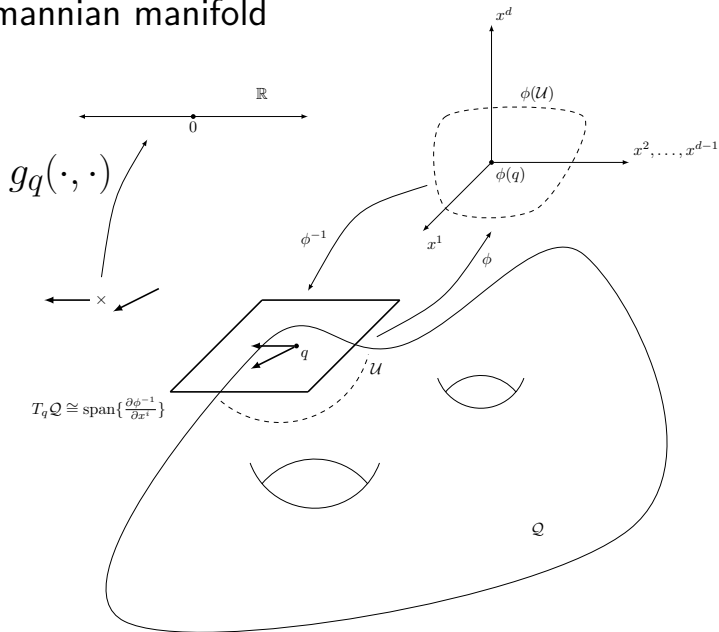
# A Riemannian manifold



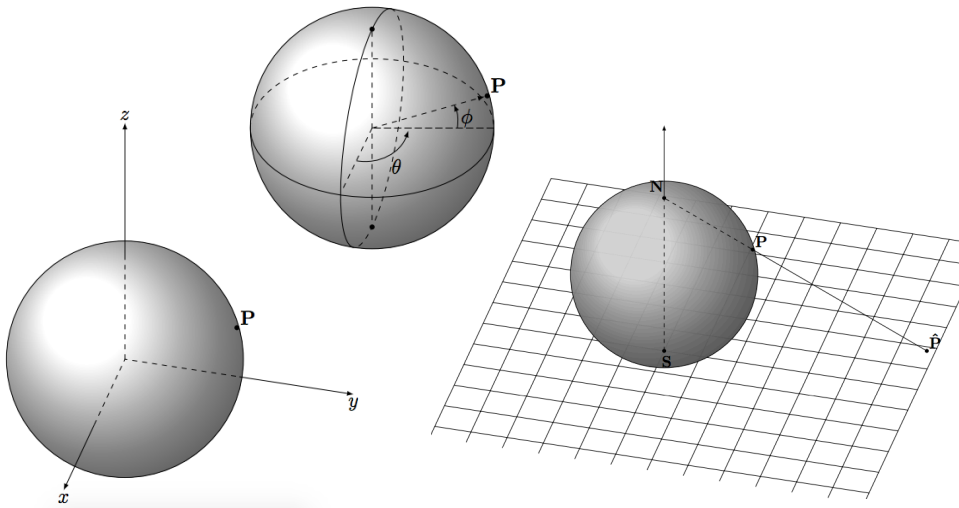
# A Riemannian manifold



# A Riemannian manifold



Pick your parameterization

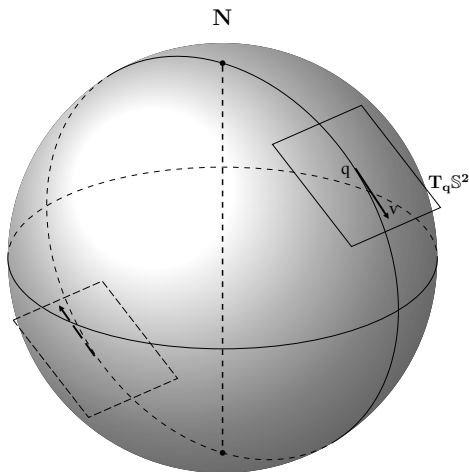


# Non-Euclidean Hamiltonian Monte Carlo

Byrne and Girolami (2013)  
extend HMC to  
Riemannian manifolds  
using *isometric  
embeddings*.

Gaussian velocities are  
generated on tangent  
space at current position.

Geodesics traverse the  
state space.



## Cartan's canonical metric

One may endow the smooth manifold of positive definite Hermitian matrices with the Riemannian metric

$$g_{\Sigma}(V_1, V_2) = \text{tr}(\Sigma^{-1} V_1 \Sigma^{-1} V_2) ,$$

for  $V_1$  and  $V_2$  any Hermitian matrices. Under this metric, the geodesic equations are

$$\Sigma(t) = \Sigma(0)^{1/2} \exp\left(t \Sigma(0)^{-1/2} V(0) \Sigma(0)^{-1/2}\right) \Sigma(0)^{1/2}$$

$$V(t) = V(0) \Sigma(0)^{-1/2} \exp\left(t \Sigma(0)^{-1/2} V(0) \Sigma(0)^{-1/2}\right) \Sigma(0)^{1/2} ,$$

but the *isometric embedding* is unknown.

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**Algorithm 1** Geodesic Lagrangian Monte Carlo

---

Let  $q = q^{(k)}$  be the  $k$ th state of the Markov chain. The next sample is generated according to the following procedure.

(a) Generate proposal state  $q^*$ :

1:  $v \sim N(0, G^{-1}(q))$

2:  $e \leftarrow -\log \pi(q) - \frac{1}{2} \log |G(q)| + \frac{1}{2} v^T G(q) v$

3:  $q^* \leftarrow q$

4: **for**  $\tau = 1, \dots, T$  **do**

5:  $v \leftarrow v + \frac{\epsilon}{2} G(q^*)^{-1} \nabla_q (\log \pi(q^*) + \frac{1}{2} \log |G(q^*)|)$

6: Progress  $(q^*, v)$  along the geodesic flow for time  $\epsilon$ .

7:  $v \leftarrow v + \frac{\epsilon}{2} G(q^*)^{-1} \nabla_q (\log \pi(q^*) + \frac{1}{2} \log |G(q^*)|)$

8: **end for**

9:  $e^* \leftarrow -\log \pi(q^*) - \frac{1}{2} \log |G(q^*)| + \frac{1}{2} v^T G(q^*) v$

(b) Accept proposal with probability  $\min\{1, \exp(e) / \exp(e^*)\}$ :

1:  $u \sim U(0, 1)$

2: **if**  $u < \exp(e - e^*)$  **then**

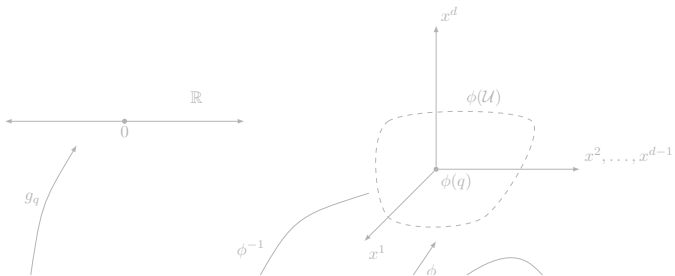
3:  $q \leftarrow q^*$

4: **end if**

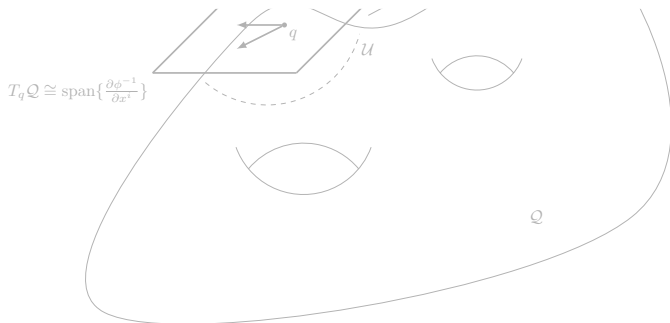
(c) Assign value  $q$  to  $q^{(k+1)}$ , the  $(k + 1)$ th state of the Markov chain.

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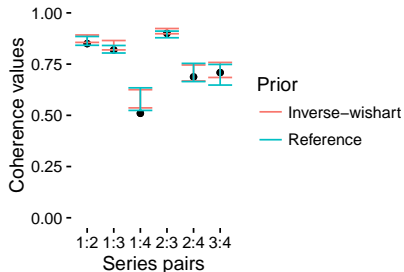
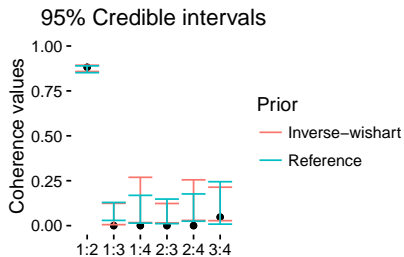
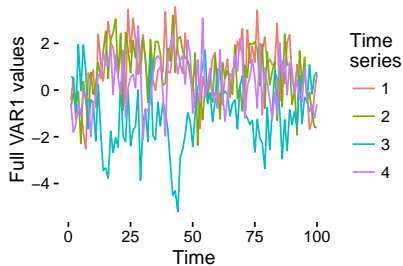
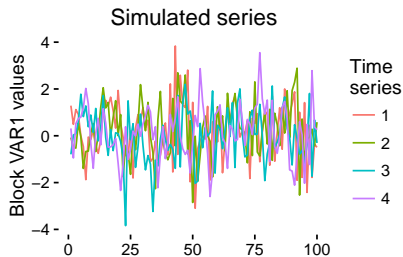




## Part 4. Spectral density estimation, revisited

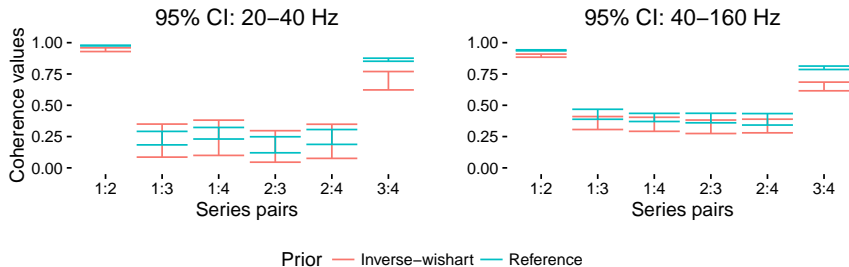
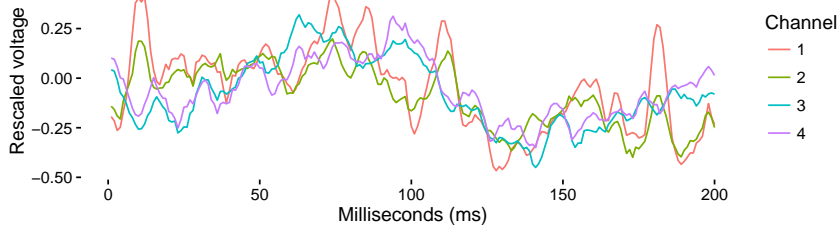


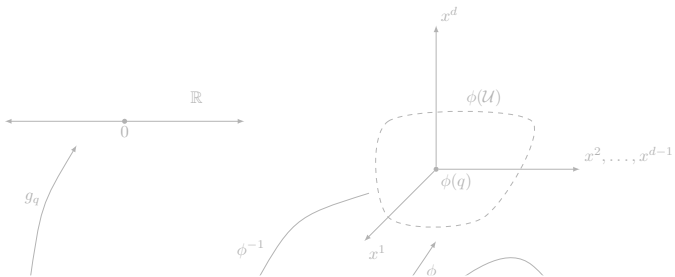
# Simulated processes



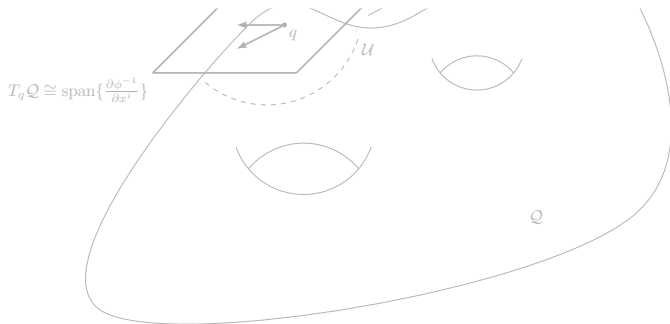
# Local field potentials

## LFP signals

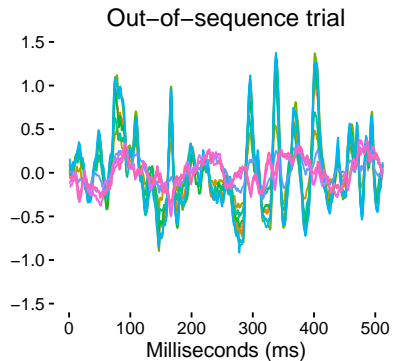
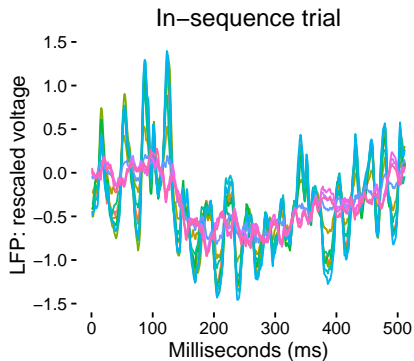




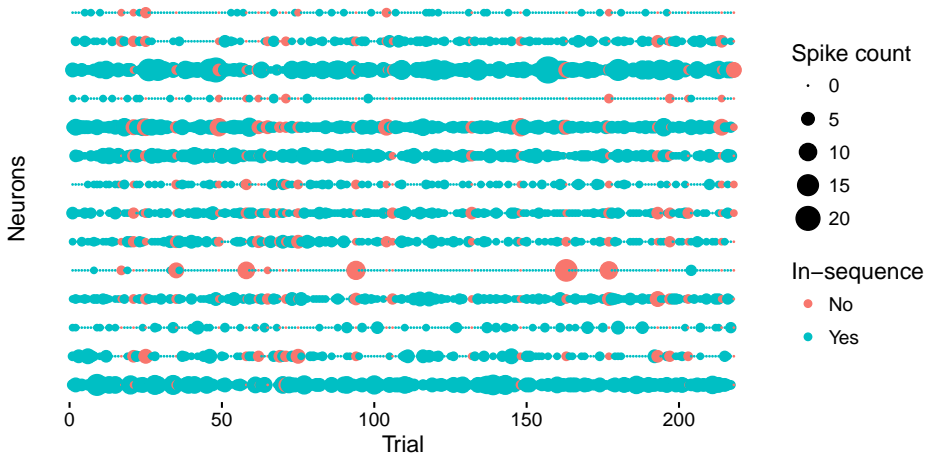
## Part 5. Bayesian neural decoding



# Local field potentials



# Neural spike trains



## sDDR: highly structured inference

LFP module:

$$\begin{aligned}\tilde{x}_i^L &= U^L \Lambda^L z_i^L + \mu^L + \epsilon_i^L, \\ \epsilon_i^L &\sim N_d(0, \sigma_L^2 I), \quad \mu^L \sim N_d(0, \tau_L^2 I), \\ z_i^L &\sim N_k(0, I), \quad \sigma_L^2, \tau_L^2, \lambda_j^L \sim \text{Cauchy}^+(0, 5), \\ j &= 1, \dots, k, \quad \lambda_j^L > \lambda_{j'}^L, \quad j > j'.\end{aligned}$$

Neural spikes module:

$$\begin{aligned}x_i^S &\sim \text{Pois}_{\otimes}(\exp\{U^S \Lambda^S z_i^S + \mu^S\}), \\ \mu^S &\sim N_d(0, \tau_S^2 I), \quad z_i^S \sim N_k(0, I) \\ \tau_S^2, \lambda_j^S &\sim \text{Cauchy}^+(0, 5), \\ j &= 1, \dots, k, \quad \lambda_j^S > \lambda_{j'}^S, \quad j > j'.\end{aligned}$$

Sequential classification module:

$$\begin{aligned}y_i &\sim \text{Bernoulli}(\text{logit}^{-1}(\beta + \beta_S^T z_i^S + \beta_L^T z_i^L)), \\ \beta &\sim N(0, 10^2), \quad \beta_S, \beta_L \sim N_k(0, 10^2 I).\end{aligned}$$

## Two loading matrix models

$$L_{d \times k} = U_{d \times k} \Lambda_{k \times k} = U_{d \times k} \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \dots & 0 & \lambda_k \end{pmatrix}$$

Model 1:

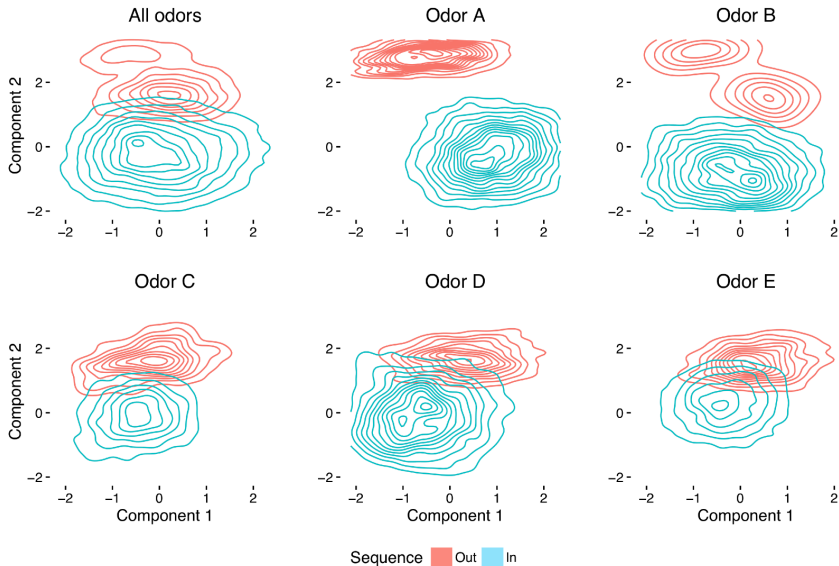
$$U \sim \text{Uni}_{\mathcal{H}}(\mathcal{O}_{d \times k}) \implies U^T U = I_k$$

Model 2:

$$U_{ij} \stackrel{iid}{\sim} N(0, 1) \implies E_{p(U)}(U^T U) \propto I_k$$



# The Information bottleneck



## Predicting sequence status

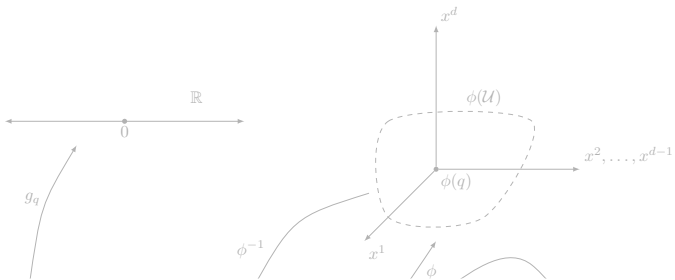
Table 2: 10-Fold cross-validation results

Method	0-1 Error		
	LFP	Spikes	Joint
sDDR, Gaussian	0.110	0.064	0.060
sDDR, Stiefel	0.106	0.069	0.064
Logistic lasso	0.106	0.092	0.087
Random forest	0.106	0.096	0.106
PLS-DA	0.106	0.073	0.096

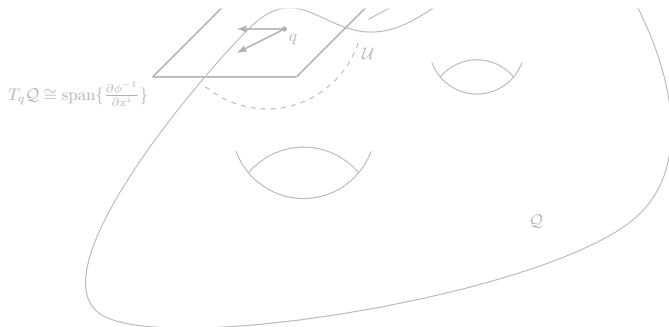
## Predicting sequence status

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PLS-DA	0.106	0.073	0.096



## Part 6. End matter



# Takeaways

- Theory *directly* contributes to applied science.
- Differential geometry enables categorical/basic improvements in Bayesian inference.
- Geometric components seamlessly integrate into advanced/hierarchical models.
- *Much* work to do in Bayesian spectral analysis.

# There's more!

- details
- information geometry and nonparametric density estimation
- $\nabla \text{Det}(A) = A^+ \text{Det}(A)$
- geodesic Monte Carlo with non-trivial mass matrix
- inference on infinite dimensional manifolds

## Many thanks to ...

- my thesis advisor, Prof. Shahbaba; my non-thesis advisor, Prof. Gillen; my mentor, Prof. Ombao;
- Alexander Vandenberg-Rodes; Shiwei Lan; Jeffrey Streets; Norbert Fortin;
- the Savage Award committee;
- Prof. Daniels;
- and ...



Thank you, Super Chris.