#### MCMC with Multiple Proposals

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#### At the Intersection of Big Data and Big Model

 Holbrook, Ji and Suchard (2022). From viral evolution to spatial contagion: a biologically modulated Hawkes model, Bioinformatics.



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- ► The number of latent variables is O(N), for N the number of observed viruses.
- ► Hawkes likelihood computations require O(N<sup>2</sup>) floating-point operations.



Proposal #1: use parallel computing to accelerate MH bottleneck, i.e., likelihood computations.



What about high dimensionality?

Proposal #2: also use parallel computing to accelerate adaptive HMC bottlenecks, i.e., log-likelihood gradient/Hessian.



What about bad geometry (non-linearity, multimodality)?

# Proposal #3: to analyze over 23k Ebola cases (2014-2016 West Africa), run the chain for 30 days using Nvidia GV100 GPU.



# Inexhaustive Taxonomy of Parallel MCMC

- Between-chain parallelization: multiple independent chains;
- ► Within-chain parallelization:
  - Model-dependent parallelization: likelihood computations;
  - Model-independent parallelization:
    - Parallel tempering;
    - Multiple-try metropolis;
    - Multiple proposals, single acceptance step.

# MCMC with Multiple Proposals

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- Schwedes and Calderhead (2021). Rao-Blackwellized parallel MCMC, AISTATS. (ML), ("Parallel MCMC")

- ► Interesting gap between 1977 and 2003
- Literature is interdisciplinary
- Non-negligible preprint count
- ► A large amount of redundant, contradictory terminology
- Much of literature focuses on weighted averages (and calls this Rao-Blackwellization)
- "Parallelizable" is often conflated with "Parallelized"
- ► I have probably not included your work

#### Efficient Multiproposal Structures

#### Multiproposal MCMC

A parallel MCMC algorithm builds a transition kernel  $P(\theta_0, d\theta)$  by:

- 1. generating *P* proposals  $\Theta_{-0} = (\theta_1, \dots, \theta_P)$  from a joint distribution  $Q(\theta_0, d\Theta_{-0}) =: q(\theta_0, \Theta_{-0})d\Theta_{-0}$ ; and
- 2. selecting the next state with probabilities

$$\pi_{p} = \frac{\pi(\boldsymbol{\theta}_{p})q(\boldsymbol{\theta}_{p},\boldsymbol{\Theta}_{-p})}{\sum_{p'=0}^{P}\pi(\boldsymbol{\theta}_{p'})q(\boldsymbol{\theta}_{p'},\boldsymbol{\Theta}_{-p'})}, \quad p \in \{0,1,\ldots,P\}.$$

This kernel maintains detailed balance and leaves  $\pi(d\theta)$  invariant.

# Multiproposal MCMC

PRO: using large numbers of proposals P helps overcome multimodality and non-linearity.



CON: requires  $\mathcal{O}(P)$  target evaluations  $\pi(\theta_p)$  and proposal evaluations  $q(\theta_p, \Theta_{-p})$ , each of the latter being  $\mathcal{O}(P)$ .

## Simplified Acceptance Probabilities

Can we somehow enforce  $q(\theta_p, \Theta_{-p}) = q(\theta_{p'}, \Theta_{-p'})$ ,  $\forall p, p' \in \{0, 1, \dots, P\}$ , to obtain simplified acceptance probabilities

$$\pi_{\boldsymbol{p}} = \frac{\pi(\boldsymbol{\theta}_{\boldsymbol{p}})}{\sum_{\boldsymbol{p}'=0}^{P} \pi(\boldsymbol{\theta}_{\boldsymbol{p}'})}, \quad \boldsymbol{p} \in \{0, 1, \dots, P\}.$$

Such structured multiproposals would result in  $O(P^2)$  time savings and simpler implementation. I consider two such approaches in

Holbrook (2023a). Generating MCMC proposals by randomly rotating the regular simplex, Journal of Multivariate Analysis. The Simplicial Sampler (elegant and expensive)

Let state space be  $\mathbb{R}^D$  and  $\mathbf{v}_1, \dots, \mathbf{v}_D \in \mathbb{R}^D$  satisfy

$$||\mathbf{v}_d - \mathbf{v}_{d'}||_2 = \lambda > 0, \quad d \neq d' \in \{1, \dots, D\}.$$

Then the simplicial sampler follows the following steps:

- 1. Sample  $D \times D$  orthonormal matrix **Q** according to Haar distribution  $\mathbf{Q} \sim \mathcal{H}(\mathcal{O}_D)$ .
- 2. Rotate and translate the simplicial vertices  $(\mathbf{0}, \mathbf{v}_1, \dots, \mathbf{v}_D) \longmapsto \mathbf{Q}(\mathbf{0}, \mathbf{v}_1, \dots, \mathbf{v}_D) + \boldsymbol{\theta}^{(s)} =: (\mathbf{0}, \boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_D).$
- 3. Draw a single sample  $\theta_d$  from  $(\theta_0, \ldots, \theta_D)$  with probability proportional to  $\pi(\theta_d)$ .

4. Set 
$$\theta^{(s+1)} = \theta_d$$

# The Simplicial Sampler (elegant and expensive)



A simplicial sampling multiproposal for D = 3. Proposal set is obtained by rotating three simplex vertices about current state  $\theta^{(s)}$ .

PRO: saves  $\mathcal{O}(D^2)$  time for D evaluations  $q(\theta_d, \Theta_{-d})$ . CON: P = D and cost is  $\mathcal{O}(D^3)$ .

# Tjelmeland Correction (a free lunch)

Tjelmeland (2004) suggests the two-step multiproposal 1.  $\bar{\boldsymbol{\theta}} \sim N_D(\boldsymbol{\theta}^{(s)}, \boldsymbol{\Sigma});$ 2.  $\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_P \stackrel{iid}{\sim} N_D(\bar{\boldsymbol{\theta}}, \boldsymbol{\Sigma}).$ 

Why? No satisfactory explanation. But it turns out that this structure leads to the desired equality (Holbrook 2023a):

$$q(oldsymbol{ heta}_p, oldsymbol{\Theta}_{-p}) = q(oldsymbol{ heta}_{p'}, oldsymbol{\Theta}_{-p'}), orall p, p' \in \{0, 1, \dots, P\}$$
 .

As promised, the resulting acceptance probabilities are:

$$\pi_{p} = \frac{\pi(\boldsymbol{\theta}_{p})}{\sum_{p'=0}^{P} \pi(\boldsymbol{\theta}_{p'})}, \quad p \in \{0, 1, \dots, P\}.$$

Only the  $\mathcal{O}(P)$  target evaluations remain in our way.

### Parallelizing Parallel MCMC

# Parallelizing Target Evaluations: CPU vs GPU



 Glatt-Holtz et al. (2022). Parallel MCMC algorithms: theoretical foundations, algorithm design, case studies, Preprint.

# The Gumbel Distribution





If  $z \sim Gumbel(0, 1)$ , then it has density and distribution functions

$$g(z) = \exp\left(-z - \exp(-z)\right)$$
 and  $G(z) = \exp\left(-\exp(-z)\right)$ .

#### Gumbel-Max Trick

We wish to sample from the discrete distribution  $\hat{p} \sim Discrete(\pi)$ for  $\hat{p} \in \{0, 1, \dots, P\}$  and we only know  $\pi^* = c\pi$  for some c > 0.

Define 
$$\lambda^* = \log \pi^* = \log \pi + \log c$$
 and suppose  $z_0, z_1, \dots, z_P \stackrel{iid}{\sim} Gumbel(0, 1).$ 

Finally, define 
$$\alpha_p^* := \lambda_p^* + z_p$$
 and  $\hat{p} = \arg \max_{p=0,\dots,P} \alpha_p^*$ .

Then the following holds (Papandreou and Yuille, 2011):

$$\Pr(\hat{p} = p) = \pi_p, \quad p = 0, 1, \dots, P.$$

Data: Initial Markov chain state 
$$\theta^{(0)}$$
; total length of Markov  
chain *S*; total number of proposals per iteration *P*.  
Result: A Markov chain  $\theta^{(1)}, \ldots, \theta^{(S)}$ .  
for  $s \in \{1, \ldots, S\}$  do  
 $\left|\begin{array}{c} \theta_0 \leftarrow \theta^{(s-1)}; \\ \bar{\theta} \leftarrow Normal_D(\theta_0, \mathbf{\Sigma}); \\ z_0 \leftarrow Gumbel(0, 1); \\ \text{for } p \in \{1, \ldots, P\} \text{ do} \\ \left|\begin{array}{c} \theta_p \leftarrow Normal_D(\bar{\theta}, \mathbf{\Sigma}); \\ z_p \leftarrow Gumbel(0, 1); \\ end \\ \hat{p} \leftarrow \arg\min_{p=0,\ldots,P} \left(f(p) := -(z_p + \log \pi(\theta_p))\right); \\ \theta^{(s)} \leftarrow \theta_{\hat{p}}; \\ end \\ return \ \theta^{(1)}, \ldots, \theta^{(S)}. \end{array}\right.$ 

# Quantum Parallel MCMC

Use a quantum circuit to obtain

$$\hat{p} = \operatorname*{arg\,min}_{p=0,...,P} \left( f(p) := -(z_p + \log \pi(\theta_p)) \right)$$



 Holbrook (2023b). A quantum parallel Markov chain Monte Carlo, JCGS.

# QPMCMC: Racing to an ESS of 100



Proposals	MCMC iterations	Target evaluations	Speedup	Efficiency gain
1,000	249,398 (200,998, 311,998)	24,988,963 (20,149,132, 31,265,011)	9.98 (9.98, 9.98)	1
5,000	14,398 (12,998, 16,998)	3,314,560 (2,989,418, 3,916,281)	21.72 (21.70, 21.74)	7.58 (6.25, 9.71)
10,000	5,998 (4,998, 6,998)	1,993,484 (1,662,592, 2,330,842)	30 (29.96, 30.26)	12.87 (8.64, 18.80)

## Ising Model Target

Consider the Ising-type lattice model over configurations  $\theta = (\theta_1, \dots, \theta_D)$  consisting of D individual spins  $\theta_d \in \{-1, 1\}$ 

$$\pi(\boldsymbol{\theta}|
ho) \propto \exp\left(
ho \sum_{(\boldsymbol{d},\boldsymbol{d}')\in\mathcal{E}} heta_{\boldsymbol{d}} heta_{\boldsymbol{d}'}
ight).$$

No need for Tjelmeland corrections when we use uniform proposals on  $\{-1,1\}^D$ . The following results are based on single-flip proposals (although not necessary).

# Ising Model Target



### Bayesian Image Segmentation

Following Hurn (1997),  $y_d$  are intensity values associated with individual pixels.

$$\begin{split} y_d | (\mu_\ell, \sigma^2, \theta_d) & \stackrel{\textit{ind}}{\sim} \mathsf{Normal}(\mu_\ell, \sigma^2) \,, \quad y_d \in [0, 255] \,, \\ \theta_d &= \ell \,, \quad d \in \{1, \dots, D\} \,, \\ \mu_\ell & \stackrel{\textit{iid}}{\sim} \mathsf{Uniform}(0, 255) \,, \quad \ell \in \{-1, 1\} \,, \\ & \frac{1}{\sigma^2} \sim \mathsf{Gamma}\left(\frac{1}{2}, \frac{1}{2}\right) \\ & \boldsymbol{\theta} \sim \mathsf{Ising}(\rho) \,, \quad \rho = 1.2 \,. \end{split}$$

# Bayesian Image Segmentation

Segmenting a 4,076-by-4,076 intensity map. Using 1,024 proposals, QPMCMC requires less than 10% the evaluations required by a conventional computer.



### **Future Directions**

## Theoretical Challenges

Glatt-Holtz et al. (2022) develop foundations for multiproposal MCMC, incorporating:

- ▶ general state space representation (Tierney, 1998);
- involutions on extended phase spaces (Nekludov et al., 2020; Glatt-Holtz et al., 2020; Andreiu et al., 2020);
- proposal cloud resampling;
- ► Metropolis-Hastings and Barker/Boltzmann acceptances.

We still lack:

- Optimal tuning guidances (D,P);
- Error bounds for biased kernels;
- nonreversible multiproposal MCMC.

## Bizarre Benefits of Bias

Schwedes and Calderhead (2021) estimate the relative reduction in MSE for Monte Carlo estimators as a function of  $\alpha$ , where  $\alpha \times P$  is the number of proposal cloud resampling iterations.



This is using the naive multiproposal

$$\boldsymbol{\theta}_1,\ldots,\boldsymbol{\theta}_P\stackrel{\textit{iid}}{\sim} N_D(0,\boldsymbol{\Sigma})$$

with full acceptance probabilities  $\pi_p \propto \pi(\theta_p) \prod_{p' \neq p} q(\theta_p, \theta_{p'})$ .

#### **Bizarre Benefits of Bias**



Starting correct algorithm away from origin

100

# Tjelmeland Correction Reduces Communication



If models are multimodal and parallelizable:

- Bayesian inversion of nonlinear PDEs;
- ► Hawkes processes (temporal, spatiotemporal, multivariate).

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## Many Proposals vs Many Chains

# Multivariate Gaussian Targets



# Massively Multimodal Targets

